Computational Verification of Anti-Unification

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Outline

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- 2. Unification
- 3. Anti-unification
- 4. Syntactic anti-unification
- 5. PVS Verification
- 6. Conclusions and Future Work

Equational Reasoning

• Equality check: s = t? • Matching: There exists σ such that $s\sigma = t$? • Unification: There exists σ such that $s\sigma = t\sigma$? • Anti-unification: There exist r, σ and ρ such that $r\sigma = s$ and $r\rho = t$?

s and t, and u are terms in some signature and σ and ρ are substitutions.

Unification

Unification

Goal: find a substitution that identifies two expressions.



- Goal: to identify two expressions.
- Method: replace variables by other expressions.

Example: for x and y variables, a and b constants, and f a function symbol,

• Identify f(x, a) and f(b, y)

- Goal: to identify two expressions.
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Example: for x and y variables, a and b constants, and f a function symbol,

- Identify f(x, a) and f(b, y)
- solution $\{x/b, y/a\}$.

Example:

- Solution σ = {x/b} for f(x, y) = f(b, y) is more general than solution γ = {x/b, y/b}.
- σ is more general than γ :

there exists δ such that $\sigma \delta = \gamma$;

 $\delta = \{y/b\}.$

Relevant questions:

- Decidability, Unification Type, Correctness and Completeness.
- When decidable, *Complexity*.
- With adequate data structures, there are linear solutions (Martelli-Montanari 1976, Petterson-Wegman 1978).

Syntactic unification is of type *unary* and linear.

Our Formalizations on Equational Reasoning



Anti-unification

Anti-unification

Goal: find the commonalities between two expressions.









- Introduced by Gordon Plotkin [Plo70] and John Reynolds [Rey70]
- First-order: syntactic [Baa91]; C, A, and AC [AEEM14]; idempotent [CK20b], unital [CK20c], semirings [Cer20], absorptive [ACBK24]
- Wigher-Order: patterns [BKLV17], top maximal and shallow generalizations variants [CK20a], equational patterns [CK19], modulo [CK20a]
- **Q** See david Cerna and Temur Kutsia survey [CK23].

Applications of anti-unification include:

- searching a large hypothesis space in inductive logic programming (ILP) for logic-based machine learning [CDEM22];
- preventing bugs and misconfigurations in software [MBK⁺20];
- **c** detecting code clones [VY19];
- searching recursion schemes for efficient parallel compilation [BBH18].

Syntactic anti-unification

Formal verification - Syntactical case

- terms $t ::= x \mid \langle \rangle \mid \langle t, t \rangle \mid f t$
- Labelled equations $E = \{s_i \triangleq t_i \mid i \leq n\}$



Configurations:

Configuration constraints

- All labels in $E_U \cup E_S$ are different,
- no repeated equations appear in E_S, and
- no label in $E_U \cup E_S$ belongs to $dom(\sigma)$.

Inference Rules

(S

$$(\text{Decompose Function}) \frac{\langle \{f \ s \stackrel{\Delta}{=} f \ t\} \cup E, S, \sigma \rangle}{\langle \{s \stackrel{\Delta}{=} t\} \cup E, S, \{x \mapsto f \ y\} \circ \sigma \rangle}$$
$$(\text{Decompose Pair}) \frac{\langle \{\langle s, u \rangle \stackrel{\Delta}{=} \langle t, v \rangle\} \cup E, S, \{x \mapsto f \ y\} \circ \sigma \rangle}{\langle \{s \stackrel{\Delta}{=} t, u \stackrel{\Delta}{=} v\} \cup E, S, \{x \mapsto \langle y, z \rangle\} \circ \sigma \rangle}$$
$$(\text{Solve Repeated}) \frac{\langle \{s \stackrel{\Delta}{=} t\} \cup E, S, \sigma \rangle}{\langle E, S, \{x \mapsto x'\} \circ \sigma \rangle} \text{ if } s \stackrel{\Delta}{=} t \in S$$
$$(\text{Solve Non-Repeated}) \frac{\langle \{s \stackrel{\Delta}{=} t\} \cup E, S, \sigma \rangle}{\langle E, \{s \stackrel{\Delta}{=} t\} \cup S, \sigma \rangle} \text{ if there is no } s \stackrel{\Delta}{=} t \in S$$

 $(\mathsf{Syntactic}) \ \frac{\langle \{s \triangleq s\} \cup E, S, \sigma \rangle}{\langle E, S, \{x \mapsto s\} \circ \sigma \rangle} \ \text{if neither decomposable nor solvable}$ 16/31

Inference Rules

Example

$$(\operatorname{DecF}) \frac{\langle \{f \langle f \langle c, b \rangle, c \rangle \stackrel{\Delta}{=} f \langle f \langle d, b \rangle, d \rangle \}, \emptyset, id \rangle}{\langle \{\langle f \langle c, b \rangle, c \rangle \stackrel{\Delta}{=} \langle f \langle d, b \rangle, d \rangle \}, \emptyset, \{x \mapsto f y\} \rangle}$$

$$(\operatorname{DecP}) \frac{\langle \{f \langle c, b \rangle \stackrel{\Delta}{=} f \langle d, b \rangle, c \stackrel{\Delta}{=} d \}, \emptyset, \{x \mapsto f \langle z_1, z_2 \rangle \} \rangle}{\langle \{c, b \rangle \stackrel{\Delta}{=} f \langle d, b \rangle, c \stackrel{\Delta}{=} d \}, \emptyset, \{x \mapsto f \langle f z_3, z_2 \rangle \} \rangle}$$

$$(\operatorname{DecP}) \frac{\langle \{c \stackrel{\Delta}{=} d, b \stackrel{\Delta}{=} b, c \stackrel{\Delta}{=} d \}, \emptyset, \{x \mapsto f \langle f \langle z, z_4 \rangle, z_2 \rangle \} \rangle}{\langle \{c \stackrel{\Delta}{=} d, b \stackrel{\Delta}{=} b, c \stackrel{\Delta}{=} d \}, \{c \stackrel{\Delta}{=} d \}, \{x \mapsto f \langle f \langle z, z_4 \rangle, z_2 \rangle \} \rangle}$$

$$(\operatorname{SolRR}) \frac{\langle \{c \stackrel{\Delta}{=} d \}, \{c \stackrel{\Delta}{=} d \}, \{c \stackrel{\Delta}{=} d \}, \{x \mapsto f \langle f \langle z, b \rangle, z_2 \rangle \} \rangle}{\langle \{c \stackrel{\Delta}{=} d \}, \{c \stackrel{\Delta}{=} d \}, \{x \mapsto f \langle f \langle z, b \rangle, z_2 \rangle \} \rangle}$$

PVS Verification

The type Configuration 🗹 and the predicate validConfiguration? 🗹 state the notions expressed in the Definition of configuration.

Solved and unsolved lists represent solved and unsolved equations of a configuration (list[AUT]). This allows the deterministic classification of the derivability type of a configuration based on the classification of its first unsolved AUT: match_DecF?, match_DecP?, match_Synt? C, and match_Sol? C.

Configurations have type (match_DecF_conf?) C, (match_DecP_conf?) C, (match_Synt_conf?) C, (match_Sol_conf?) C or, when the unsolved part is empty, (normal_configuration?) C. The rules (DecF), (DecP) and (Synt) were specified as function declarations DecF(c) \Box , DecP(c) \Box , and Synt(c) \Box , respectively. The solve rules (SoIR) and (SoINR) were integrated into a unique rule Solve(c) \Box

To automatize the proofs of *termination*, *configuration validity*, and *preservation of niceness* of the Antiunify algorithm, these properties were encoded in the types of the functions representing the rules.

- E.g., consider the type of the function DecF(c) \square .
 - Its input type is defined as (match_DecF_conf?).
 - Its output type denotes those valid configurations cp, with the required properties to automatize proofs.

The Antiunify C algorithm is defined in PVS as a recursive function of type [(validConfiguration?) -> (validConfiguration?)].

By restricting the types for the functions specifying the inference rules (DecF), (DecP), (Solve), and (Synt), PVS automatically proves Antiunify's termination and that every output of the Antiunify algorithm fulfills the validConfiguration? predicate. Three auxiliary lemmas about invariants and configuration preservation are highlighted.

1. antiunify_sub_preserves_terms States that if a t∈
range(c'subs) and vars(t)∩labels(c'unsolved) = Ø then
(Antiunify(c)'subs)(t) = (c'subs)(t).

Applied twice to (2) and once to (SolveR).

- 2. antiunify_dom_sub_preserves_vars_unsolved states
 that domain(Antiunify(c)'subs)∩ vars(c'unsolved) = Ø.
 Applied once to (Synt).
- 3. antiunify_solved_labels_preserve_vars_unsolved ☑
 states that labels(Antiunify(c)'solved) ∩
 vars(c'unsolved) = Ø. Applied twice to (Synt).

No preservation lemma was required by (DecF) and (DecP), and (SolveNR) depends on simple preservation lemmas. 21 / 31

The proof of the soundness theorem, antiunif_is_sound follows by induction on the size of configurations and case analysis. Surprising the resulting higher complexity of the formal analysis of the "simpler" analytical cases of the rules (Syntactic) and (SolveR).

Table 1: Formalization in numbers

PVS theory	Formulas	TCCs	Inference	Proof size	Dependencies
			Rule	(# lines)	(# lines)
Terms	119	37	-	-	-
Substitution	115	18			
Anti-unification	116	41	(DecF)	64	-
			(DecP)	140	-
			(Synt)	269	1624
			(SolveR)	245	663
			(SolveNR)	63	111

Anti-unification modulo types

Theory	Anti-unification type	References	
Syntactic	1	[Plo70, Rey70]	
А	ω	[AEEM14]	
С	ω	[AEEM14]	
† (U)1	ω	[CK20c]	
(U) ^{≥2}	0	[CK20c]	
‡ a	∞	[ACBK24]	
a(C)	∞	[ACBK24]	

(†)Unital: { $f(\iota_f, x) = x, f(x, \iota_f) = x$ } (‡)Absorptive: { $f(\varepsilon_f, x) = \varepsilon_f, f(x, \varepsilon_f) = \varepsilon_f$ }

Conclusions and Future Work

Conclusions

- Although anti-unification has become of increasing interest, formal certification of anti-unification algorithms has not been explored except for the simplest syntactic case [ARdLK⁺25].
- The development of procedures to solve anti-unification modulo theories is crucial.
- Only recently, anti-unification modulo a-, C-, and (aC)-symbols have been addressed. Procedures combining such properties have been shown to be challenging from theoretical and practical perspectives [ACBK24].

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